Minutes 09-05-2022

Presentation deadline 19th Mai

Revision positional sensors

Deeper look at simulation methods that is not gazebo

Start sprint 2

URDF file / svg file contact Ismail (Serkan)

Simulation, leave complexity out by simulation more parts ()

simulation environment (Marios)

Start coding

Finalize design

State machine (Celine)

deadlock validation

Finalize material list and see what extra components we need (Metehan)

Gripper (Can)